



Dynamics of Nonholonomic Systems (Translations of Mathematical Monographs, V. 33)

Ju I Neimark and N A Fufaev

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The goal of this book is to give a comprehensive and systematic exposition of the mechanics of nonholonomic systems, including the kinematics and dynamics of nonholonomic systems with classical nonholonomic constraints, the theory of stability of nonholonomic systems, technical problems of the directional stability of rolling systems, and the general theory of electrical machines. The book contains a large number of examples and illustrations.

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