



Duty-Split Approach in Robotic Surgery (Robotics Research and Technology)

Rinaldo C. Michelini, Silvia Frumento, Roberto P. Razzoli

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Mini-invasive surgery deserves increasing attention to lower post-operative stays in hospitals and to lessen fall-off complications. This new book is devoted to surgical robotics, with a focus on technology and design issues of the remote-mode operation assistants. The investigation leads to define the technical characteristics of a CRHA, co-robotic handling appliance, to be purposely developed, to support the duty-split approach surgical planner.

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